

**VITELIC**

**V53C256A FAMILY**  
**HIGH PERFORMANCE, LOW POWER**  
**256K X 1 BIT FAST PAGE MODE**  
**CMOS DYNAMIC RAM**

**2**

| <b>HIGH PERFORMANCE V53C256A</b>               | <b>60/60L</b> | <b>70/70L</b> | <b>80/80L</b> | <b>10/10L</b> |
|------------------------------------------------|---------------|---------------|---------------|---------------|
| Max. RAS Access Time, ( $t_{RAC}$ )            | 60 ns         | 70 ns         | 80 ns         | 100 ns        |
| Max. Column Address Access Time, ( $t_{CAA}$ ) | 30 ns         | 35 ns         | 40 ns         | 45 ns         |
| Max. CAS Access Time, ( $t_{CAC}$ )            | 15 ns         | 15 ns         | 20 ns         | 25 ns         |
| Min. Fast Page Mode Cycle Time, ( $t_{PC}$ )   | 45 ns         | 50 ns         | 55 ns         | 60 ns         |
| Min. Read-Write Cycle Time, ( $t_{RC}$ )       | 115 ns        | 130 ns        | 145 ns        | 175 ns        |

| <b>LOW POWER V53C256AL</b>               | <b>60L</b> | <b>70L</b> | <b>80L</b> | <b>10L</b> |
|------------------------------------------|------------|------------|------------|------------|
| Max. CMOS Standby Current, ( $I_{DD6}$ ) | 1.2 mA     | 1.2 mA     | 1.2 mA     | 1.2 mA     |

**Features**

- Low power dissipation for V53C256A-10
  - Operating Current—60 mA max.
  - TTL Standby Current—3.5 mA max.
- Low CMOS Standby Current
  - V53C256A—3.0 mA max.
  - V53C256AL—1.2 mA max.
- Read-Modify-Write, RAS-Only Refresh, CAS-before-RAS Refresh capability
- Common I/O capability
- Fast Page Mode operation for a sustained data rate greater than 21 MHz.
- 256 Refresh cycles/4 ms
- Standard packages are 16 pin Plastic DIP and 18 pin PLCC

**Description**

The Vitelic V53C256A is a high speed 262,144 x 1 bit CMOS dynamic random access memory. Fabricated with Vitelic's VICMOS III technology, the V53C256A offers a combination of size and features

unattainable with NMOS technology: Fast Page Mode for high data bandwidth, fast usable speed, CMOS standby current and, for the V53C256AL, reduced CMOS standby mode supply current ( $I_{DD6}$ ).

All inputs and outputs are TTL compatible. Input and output capacitances are significantly lowered to allow increased system performance. Fast Page Mode operation allows random or sequential access of up to 512 bits within a row with cycle times as short as 50 ns. Because of static circuitry, the CAS clock is not in the critical timing path. The flow-through column address latches allow address pipelining while relaxing many critical timing requirements for fast usable speed. These features make the V53C256 ideally suited for cache based mainframe and mini computers, graphics, digital signal processing and high performance microprocessor systems.

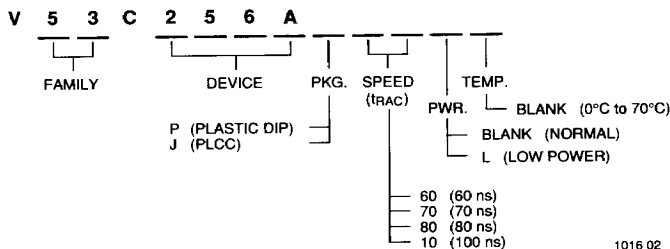
The V53C256AL -10 offers a maximum data retention power of 10 mW when operating in CMOS standby mode and performing RAS-only or CAS-before-RAS refresh cycles. This mode is entered by holding RAS at a voltage greater than  $V_{DD}-0.2$  when it is inactive.

**Device Usage Chart**

| Operating Temperature Range | Package Outline |   | Access Time (ns) |    |    |     | Power |      | Temperature Mark |
|-----------------------------|-----------------|---|------------------|----|----|-----|-------|------|------------------|
|                             | P               | J | 60               | 70 | 80 | 100 | Low   | Std. |                  |
| 0°C to 70°C                 | •               | • | •                | •  | •  | •   | •     | •    | Blank            |

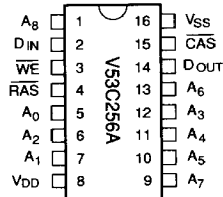
V53C256A Rev.00 June 1990

| Package     | Pkg. | Pin Count |
|-------------|------|-----------|
| Plastic DIP | P    | 16        |
| PLCC        | J    | 18        |

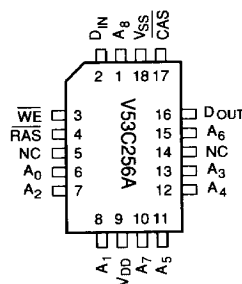


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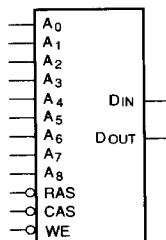
**16 Lead Plastic DIP  
PIN CONFIGURATION  
Top View**



**18 Lead PLCC Package  
PIN CONFIGURATION  
Top View**



### LOGIC SYMBOL



1016 03

### Absolute Maximum Ratings\*

Ambient Temperature

Under Bias ..... -10°C to +80°C

Storage Temperature (plastic) .... -55°C to +125°C

Voltage on any Pin Except V<sub>DD</sub>

Relative to V<sub>SS</sub> ..... -1.0 V to +7.0 V

Voltage on V<sub>DD</sub> relative to V<sub>SS</sub> ..... -1.0 V to +7.0 V

Data Out Current ..... 50 mA

Power Dissipation ..... 1.0 W

### Capacitance\*

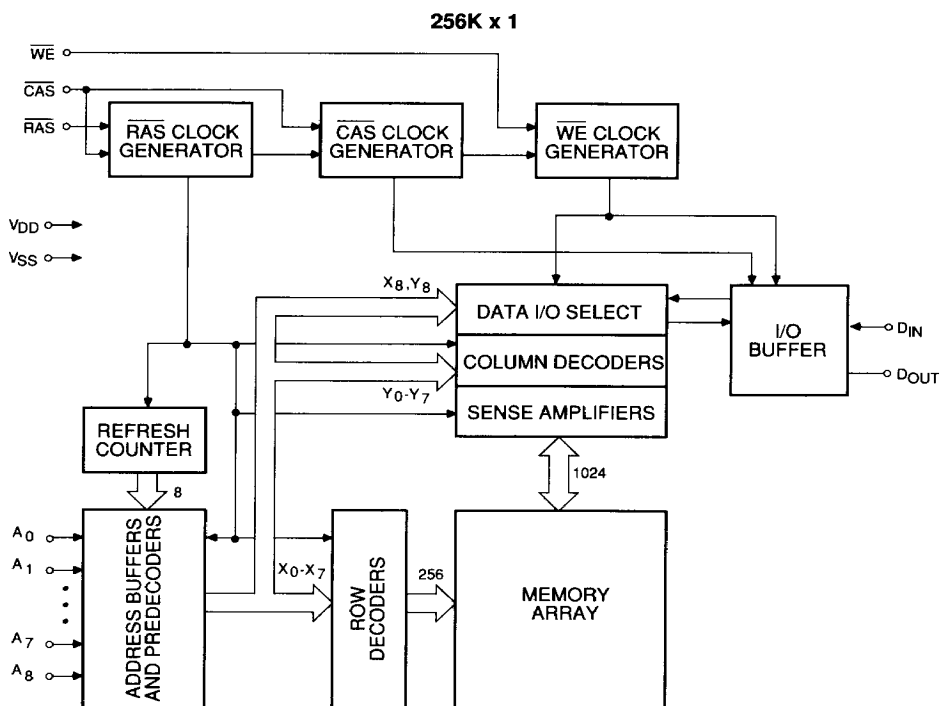
T<sub>A</sub> = 25°C, V<sub>DD</sub> = 5 V ±10%, V<sub>SS</sub> = 0 V

| Symbol           | Parameter                | Typ. | Max. | Unit |
|------------------|--------------------------|------|------|------|
| C <sub>IN1</sub> | Address, D <sub>IN</sub> | 3    | 4    | pF   |
| C <sub>IN2</sub> | RAS, CAS, WE             | 4    | 5    | pF   |
| C <sub>OUT</sub> | D <sub>OUT</sub>         | 4    | 6    | pF   |

\*Note: Capacitance is sampled and not 100% tested

\*Note: Operation above Absolute Maximum Ratings can adversely affect device reliability.

**Block Diagram**



1016 01

**DC and Operating Characteristics**

$T_A = 0^\circ\text{C}$  to  $70^\circ\text{C}$ ,  $V_{DD} = 5\text{ V} \pm 10\%$ ,  $V_{SS} = 0\text{ V}$ , unless otherwise specified.

| Symbol    | Parameter                                               | Access Time | V53C256A |              | V53C256AL |              | Unit          | Test Conditions                                                                      | Notes |
|-----------|---------------------------------------------------------|-------------|----------|--------------|-----------|--------------|---------------|--------------------------------------------------------------------------------------|-------|
|           |                                                         |             | Min.     | Max.         | Min.      | Max.         |               |                                                                                      |       |
| $I_{LI}$  | Input Leakage Current<br>(any input pin)                |             | -10      | 10           | -10       | 10           | $\mu\text{A}$ | $V_{SS} \leq V_{IN} \leq V_{DD}$                                                     |       |
| $I_{LO}$  | Output Leakage Current<br>(for High-Z State)            |             | -10      | 10           | -10       | 10           | $\mu\text{A}$ | $V_{SS} \leq D_{OUT} \leq V_{DD}$<br>RAS, CAS at $V_{IH}$                            |       |
| $I_{DD1}$ | $V_{DD}$ Supply Current,<br>Operating                   | 60          |          | 80           |           | 80           | mA            | $t_{RC} = t_{RC}(\text{min.})$                                                       | 1,2   |
|           |                                                         | 70          |          | 70           |           | 70           |               |                                                                                      |       |
|           |                                                         | 80          |          | 65           |           | 65           |               |                                                                                      |       |
|           |                                                         | 100         |          | 60           |           | 60           |               |                                                                                      |       |
| $I_{DD2}$ | $V_{DD}$ Supply Current,<br>TTL Standby                 |             |          | 3.5          |           | 2.0          | mA            | RAS, CAS at $V_{IH}$<br>other inputs $\geq V_{SS}$                                   |       |
| $I_{DD3}$ | $V_{DD}$ Supply Current,<br>RAS-Only Refresh            | 60          |          | 80           |           | 80           | mA            | $t_{RC} = t_{RC}(\text{min.})$                                                       | 2     |
|           |                                                         | 70          |          | 70           |           | 70           |               |                                                                                      |       |
|           |                                                         | 80          |          | 60           |           | 60           |               |                                                                                      |       |
|           |                                                         | 100         |          | 50           |           | 50           |               |                                                                                      |       |
| $I_{DD4}$ | $V_{DD}$ Supply Current,<br>Fast Page Mode<br>Operation | 60          |          | 50           |           | 50           | mA            | Minimum Cycle                                                                        | 1,2   |
|           |                                                         | 70          |          | 45           |           | 45           |               |                                                                                      |       |
|           |                                                         | 80          |          | 40           |           | 40           |               |                                                                                      |       |
|           |                                                         | 100         |          | 35           |           | 35           |               |                                                                                      |       |
| $I_{DD5}$ | $V_{DD}$ Supply Current,<br>Standby, Output Enabled     |             |          | 4            |           | 2.5          | mA            | RAS = $V_{IH}$ , CAS = $V_{IL}$<br>other inputs $\geq V_{SS}$                        | 1     |
| $I_{DD6}$ | $V_{DD}$ Supply Current,<br>CMOS Standby                |             |          | 3            |           | 1.2          | mA            | RAS $\geq V_{DD} - 0.2\text{ V}$ ,<br>CAS = $V_{IH}$ ,<br>other inputs $\geq V_{SS}$ |       |
| $V_{IL}$  | Input Low Voltage<br>(all inputs)                       |             | -1       | 0.8          | -1        | 0.8          | V             |                                                                                      | 3     |
| $V_{IH}$  | Input High Voltage<br>(all inputs)                      |             | 2.4      | $V_{DD} + 1$ | 2.4       | $V_{DD} + 1$ | V             |                                                                                      | 3     |
| $V_{OL}$  | Output Low Voltage                                      |             |          | 0.4          |           | 0.4          | V             | $I_{OL} = 4.2\text{ mA}$                                                             |       |
| $V_{OH}$  | Output High Voltage                                     |             | 2.4      |              | 2.4       |              | V             | $I_{OH} = -5\text{ mA}$                                                              |       |

**AC Characteristics**
 $T_A = 0^\circ\text{C to } 70^\circ\text{C}$ ,  $V_{DD} = 5\text{ V} \pm 10\%$ ,  $V_{SS} = 0\text{ V}$ , unless otherwise noted

| #  | JEDEC Symbol    | Symbol       | Parameter                                             | 60/60L |      | 70/70L |      | 80/80L |      | 10/10L |          | Unit | Notes |
|----|-----------------|--------------|-------------------------------------------------------|--------|------|--------|------|--------|------|--------|----------|------|-------|
|    |                 |              |                                                       | Min.   | Max. | Min.   | Max. | Min.   | Max. | Min.   | Max.     |      |       |
| 1  | $t_{RL1RH1}$    | $t_{RAS}$    | $\overline{RAS}$ Pulse Width                          | 60     | 75K  | 70     | 75K  | 80     | 75K  | 100    | 75K      | ns   |       |
| 2  | $t_{RL2RL2}$    | $t_{RC}$     | Read or Write Cycle Time                              | 115    |      | 130    |      | 145    |      | 175    |          | ns   |       |
| 3  | $t_{RH2RL2}$    | $t_{RP}$     | $\overline{RAS}$ Precharge Time                       | 45     |      | 50     |      | 55     |      | 65     |          | ns   |       |
| 4  | $t_{AVRL2}$     | $t_{ASR}$    | Row Address Setup Time                                | 0      |      | 0      |      | 0      |      | 0      |          | ns   |       |
| 5  | $t_{RL1AX}$     | $t_{RAH}$    | Row Address Hold Time                                 | 10     |      | 15     |      | 15     |      | 15     |          | ns   |       |
| 6  | $t_{AVRH1}$     | $t_{CAR}$    | Column Address to $\overline{RAS}$ Setup Time         | 30     |      | 35     |      | 40     |      | 45     |          | ns   |       |
| 7  | $t_{RL1AV}$     | $t_{RAD}$    | $\overline{RAS}$ to Column Address Delay Time         | 15     | 30   | 20     | 35   | 20     | 40   | 20     | 55       | ns   | 4     |
| 8  | $t_{AVCL2}$     | $t_{ASC}$    | Column Address Setup Time                             | 0      |      | 0      |      | 0      |      | 0      |          | ns   |       |
| 9  | $t_{CL1AX}$     | $t_{CAH}$    | Column Address Hold Time                              | 10     |      | 15     |      | 15     |      | 20     |          | ns   |       |
| 10 | $t_{RL1CL1}$    | $t_{RCD}$    | $\overline{RAS}$ to $\overline{CAS}$ Delay            | 20     | 45   | 25     | 55   | 25     | 60   | 25     | 75       | ns   | 5     |
| 11 | $t_{RL1QV}$     | $t_{RAC}$    | Access Time from $\overline{RAS}$                     |        | 60   |        | 70   |        | 80   |        | 100      | ns   | 6,7,8 |
| 12 | $t_{AVQV}$      | $t_{CAA}$    | Access Time from Column Address                       |        | 30   |        | 35   |        | 40   |        | 45<br>15 | ns   | 8,9   |
| 13 | $t_{CL1QV}$     | $t_{CAC}$    | Access Time from $\overline{CAS}$                     |        | 15   |        | 15   |        | 20   |        | 25       | ns   | 8,15  |
| 14 | $t_{CL1CH1(R)}$ | $t_{CAS(R)}$ | $\overline{CAS}$ Pulse Width in Read Cycle            | 15     | 75K  | 15     | 75K  | 20     | 75K  | 25     | 75K      | ns   |       |
| 15 | $t_{CL1RH1(R)}$ | $t_{RSH(R)}$ | $\overline{RAS}$ Hold Time (Read Cycle)               | 15     |      | 15     |      | 20     |      | 25     |          | ns   |       |
| 16 | $t_{WH2CL2}$    | $t_{RCS}$    | Read Command Setup Time                               | 0      |      | 0      |      | 0      |      | 0      |          | ns   |       |
| 17 | $t_{CH2WX}$     | $t_{RCH}$    | Read Command Hold Time Referenced to $\overline{CAS}$ | 0      |      | 5      |      | 5      |      | 5      |          | ns   | 10    |
| 18 | $t_{RH2WX}$     | $t_{RRH}$    | Read Command Hold Time Referenced to $\overline{RAS}$ | 5      |      | 5      |      | 5      |      | 5      |          | ns   | 10    |
| 19 | $t_{CH2RL2}$    | $t_{CRP}$    | $\overline{CAS}$ to $\overline{RAS}$ Precharge Time   | 10     |      | 15     |      | 15     |      | 15     |          | ns   |       |
| 20 | $t_{CH2QX}$     | $t_{OFF}$    | Output Buffer Turn Off Delay                          | 0      | 15   | 0      | 15   | 0      | 20   | 0      | 25       | ns   | 11    |

**AC Characteristics (Cont'd.)**

| #  | JEDEC Symbol      | Symbol       | Parameter                                                            | 60/60L |      | 70/70L |      | 80/80L |      | 10/10L |      | Unit | Notes |
|----|-------------------|--------------|----------------------------------------------------------------------|--------|------|--------|------|--------|------|--------|------|------|-------|
|    |                   |              |                                                                      | Min.   | Max. | Min.   | Max. | Min.   | Max. | Min.   | Max. |      |       |
| 21 | $t_{CH2QV}$       | $t_{OH}$     | Data Hold Time from $\overline{CAS}$                                 | 0      |      | 0      |      | 0      |      | 0      |      | ns   | 11    |
| 22 | $t_{WL1WH1}$      | $t_{WP}$     | Write Pulse Width                                                    | 10     |      | 15     |      | 15     |      | 20     |      | ns   |       |
| 23 | $t_{CH2CL2}$      | $t_{CP}$     | $\overline{CAS}$ Precharge Time                                      | 10     |      | 15     |      | 15     |      | 20     |      | ns   |       |
| 24 | $t_{RL1AX}$       | $t_{AR}$     | Column Address Hold Time from $\overline{RAS}$                       | 50     |      | 55     |      | 60     |      | 70     |      | ns   |       |
| 25 | $t_{CL1CH1(W)}$   | $t_{CAS(W)}$ | $\overline{CAS}$ Pulse Width in Write Cycle                          | 20     |      | 20     |      | 25     |      | 30     |      | ns   |       |
| 26 | $t_{CL1RH1(W)}$   | $t_{RSH(W)}$ | $\overline{RAS}$ or $\overline{CAS}$ Hold Time in Write Cycle        | 20     |      | 25     |      | 25     |      | 30     |      | ns   |       |
| 27 | $t_{RL1WH1}$      | $t_{WCR}$    | Write Command Hold Time from $\overline{RAS}$                        | 50     |      | 55     |      | 60     |      | 70     |      | ns   |       |
| 28 | $t_{WL1CL2}$      | $t_{WCS}$    | Write Command Setup Time                                             | 0      |      | 0      |      | 0      |      | 0      |      | ns   | 12,13 |
| 29 | $t_{CL1WH1}$      | $t_{WCH}$    | Write Command Hold Time                                              | 10     |      | 15     |      | 15     |      | 20     |      | ns   |       |
| 30 | $t_{DVWL2}$       | $t_{DS}$     | Data In Setup Time                                                   | 0      |      | 0      |      | 0      |      | 0      |      | ns   | 14    |
| 31 | $t_{WH1DX}$       | $t_{DH}$     | Data In Hold Time                                                    | 15     |      | 15     |      | 15     |      | 20     |      | ns   | 14    |
| 32 | $t_{RL1DX}$       | $t_{DHR}$    | Data In Hold Time Referenced to $\overline{RAS}$                     | 50     |      | 55     |      | 60     |      | 70     |      | ns   |       |
| 33 | $t_{RL2RL2(RMW)}$ | $t_{RWC}$    | Read-Modify-Write Cycle Time                                         | 140    |      | 155    |      | 175    |      | 210    |      | ns   |       |
| 34 | $t_{RL1RH1(RMW)}$ | $t_{RRW}$    | Read-Modify-Write Cycle $\overline{RAS}$ Pulse Width                 | 85     |      | 95     |      | 110    |      | 135    |      | ns   |       |
| 35 | $t_{RL1WL2}$      | $t_{RWD}$    | $\overline{RAS}$ to $\overline{WE}$ Delay In Read-Modify-Write Cycle | 60     |      | 70     |      | 80     |      | 100    |      | ns   | 12    |
| 36 | $t_{CL1WL2}$      | $t_{CWD}$    | $\overline{CAS}$ to $\overline{WE}$ Delay                            | 15     |      | 15     |      | 20     |      | 25     |      | ns   | 12    |
| 37 | $t_{AVWL2}$       | $t_{AWD}$    | Column Address to $\overline{WE}$ Delay                              | 30     |      | 35     |      | 40     |      | 45     |      | ns   | 12    |
| 38 | $t_{CH2QV}$       | $t_{CAP}$    | Access Time from Column Precharge                                    |        | 40   |        | 45   |        | 50   |        | 55   | ns   | 15    |
| 39 | $t_{CL2CL2(R)}$   | $t_{PC}$     | Fast Page Mode Read or Write Cycle Time                              | 45     |      | 50     |      | 55     |      | 60     |      | ns   |       |

**AC Characteristics (Cont'd.)**

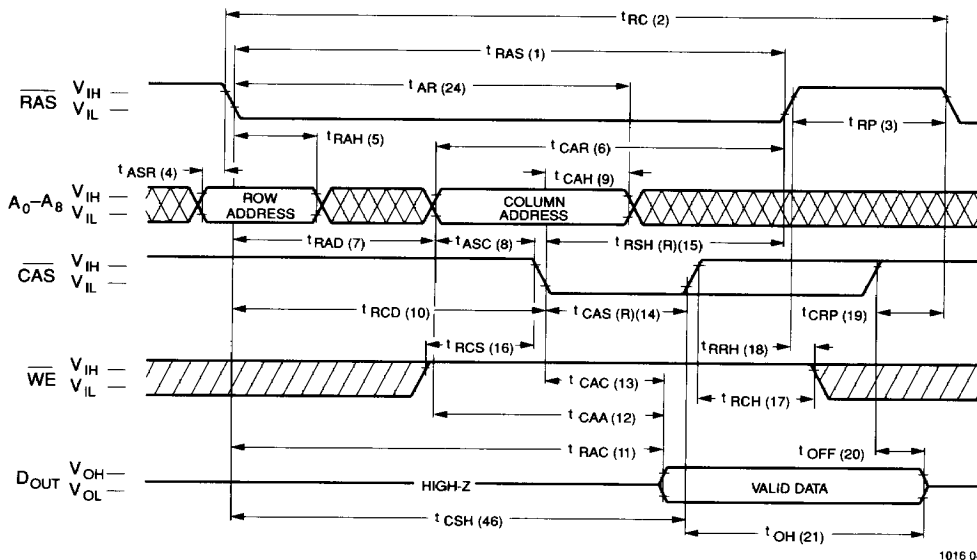
| #  | JEDEC Symbol          | Symbol    | Parameter                                                                         | 60/60L |      | 70/70L |      | 80/80L |      | 10/10L |      | Unit | Notes |
|----|-----------------------|-----------|-----------------------------------------------------------------------------------|--------|------|--------|------|--------|------|--------|------|------|-------|
|    |                       |           |                                                                                   | Min.   | Max. | Min.   | Max. | Min.   | Max. | Min.   | Max. |      |       |
| 40 | $t_{CL2CL2}$<br>(RMW) | $t_{PCM}$ | Fast Page Mode Read-Modify-Write Cycle Time                                       | 70     |      | 75     |      | 85     |      | 95     |      | ns   |       |
| 41 | $t_{WL1RH1}$          | $t_{RWL}$ | Write Command to $\overline{RAS}$ Lead Time                                       | 20     |      | 20     |      | 25     |      | 30     |      | ns   |       |
| 42 | $t_{WL1CH1}$          | $t_{CWL}$ | Write Command to $\overline{CAS}$ Lead Time                                       | 20     |      | 20     |      | 25     |      | 30     |      | ns   |       |
| 43 | $t_{RH2CL2}$          | $t_{RPC}$ | $\overline{RAS}$ to $\overline{CAS}$ Precharge Time                               | 0      |      | 0      |      | 0      |      | 0      |      | ns   |       |
| 44 | $t_{CL1RL2}$          | $t_{CSR}$ | $\overline{CAS}$ Setup Time<br>$\overline{CAS}$ -before- $\overline{RAS}$ Refresh | 10     |      | 10     |      | 10     |      | 10     |      | ns   |       |
| 45 | $t_{RL1CH1}$          | $t_{CHR}$ | $\overline{CAS}$ Hold Time<br>$\overline{CAS}$ -before- $\overline{RAS}$ Cycle    | 15     |      | 20     |      | 25     |      | 30     |      | ns   |       |
| 46 | $t_{RL1CH1}$          | $t_{CSH}$ | $\overline{CAS}$ Hold Time                                                        | 60     |      | 70     |      | 80     |      | 100    |      | ns   |       |
| 47 | $t_T$                 | $t_T$     | Transition Time<br>(Rise and Fall)                                                | 3      | 25   | 3      | 25   | 3      | 25   | 3      | 25   | ns   | 16    |
|    |                       | $t_{RI}$  | Refresh Interval<br>(256 Cycles)                                                  | 4      |      | 4      |      | 4      |      | 4      |      | ms   | 17    |

**Notes:**

1.  $I_{DD}$  is dependent on output loading when the device output is selected. Specified  $I_{DD}$  (max.) is measured with the output open.
2.  $I_{DD}$  is dependent upon the number of address transitions. Specified  $I_{DD}$  (max.) is measured with a maximum of two transitions per address cycle in Fast Page Mode.
3. Specified  $V_{IL}$  (min.) is steady state operation. During transitions,  $V_{IL}$  (min.) may undershoot to  $-1.0$  V for periods not to exceed 20 ns. All AC parameters are measured with  $V_{IL}$  (min.)  $\geq V_{SS}$  and  $V_{IH}$  (max.)  $\leq V_{DD}$ .
4. Operation within the  $t_{RAD}$  (max.) limit ensures that  $t_{RAC}$  (max.) can be met.  $t_{RAD}$  (max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$  (max.), the access time is controlled by  $t_{CAA}$  and  $t_{CAC}$ .
5.  $t_{RCD}$  (max.) is specified for reference only. Operation within  $t_{RCD}$  (max.) and  $t_{RAD}$  (max.) limits ensure that  $t_{RAC}$  (max.) and  $t_{CAA}$  (max.) can be met. If  $t_{RCD}$  is greater than the specified  $t_{RCD}$  (max.), the access time is controlled by  $t_{CAA}$  and  $t_{CAC}$ .
6. Assumes that  $t_{RAD} \leq t_{RAD}$  (max.). If  $t_{RAD}$  is greater than  $t_{RAD}$  (max.),  $t_{RAC}$  will increase by the amount that  $t_{RAD}$  exceeds  $t_{RAD}$  (max.).
7. Assumes that  $t_{RCD} \leq t_{RCD}$  (max.). If  $t_{RCD}$  is greater than  $t_{RCD}$  (max.),  $t_{RAC}$  will increase by the amount that  $t_{RCD}$  exceeds  $t_{RCD}$  (max.).
8. Measured with a load equivalent to two TTL inputs and 100 pF in parallel.
9. Assumes that  $t_{RAD} \geq t_{RAD}$  (max.).
10. Either  $t_{RRH}$  or  $t_{RCH}$  must be satisfied for a Read Cycle to occur.
11.  $t_{OFF}$  and  $t_{ON}$  define the time at which  $D_{OUT}$  reaches an open circuit condition and are not referenced to the output voltage levels.
12.  $t_{WCS}$ ,  $t_{RWD}$ ,  $t_{AWD}$  and  $t_{CWD}$  are not restrictive operating parameters.
13.  $t_{WCS}$  (min.) must be satisfied in an Early Write Cycle.
14.  $t_{DS}$  and  $t_{DH}$  are referenced to the later occurrence of  $\overline{CAS}$  or  $\overline{WE}$ .
15. Access time is determined by the longer of  $t_{CAA}$ ,  $t_{CAC}$ , or  $t_{CAP}$ .
16.  $t_T$  is measured between  $V_{IH}$  (min.) and  $V_{IL}$  (max.). AC measurements assume  $t_T = 5$  ns.
17. An initial 200  $\mu$ s pause and 8  $\overline{RAS}$ -containing cycles are required when exiting an extended period of bias without clocks. An extended period of time without clocks is defined as one that exceeds the specified Refresh Interval.

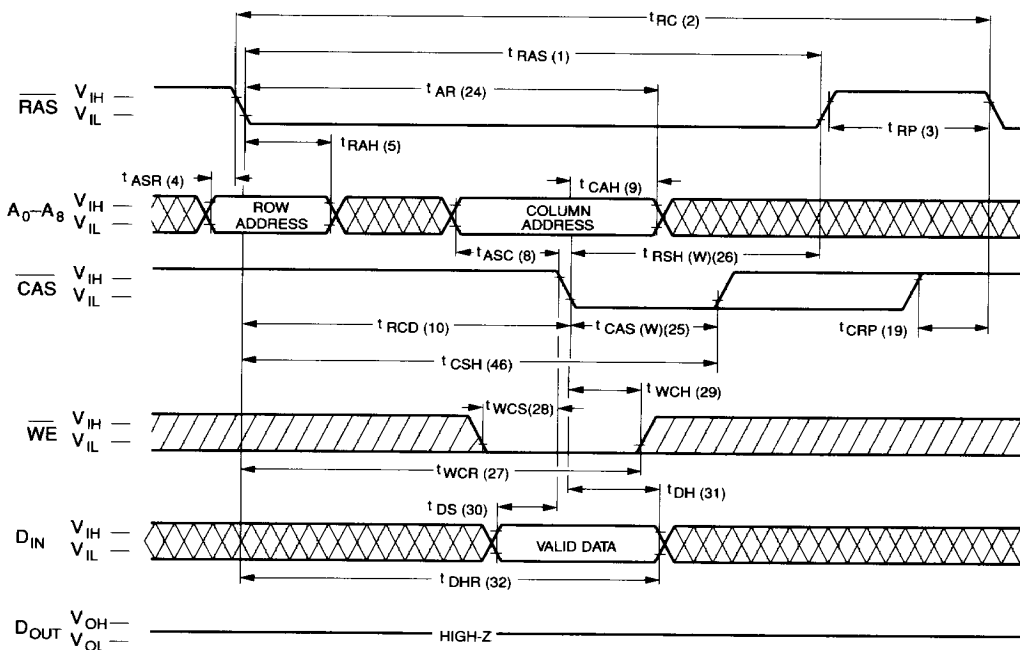


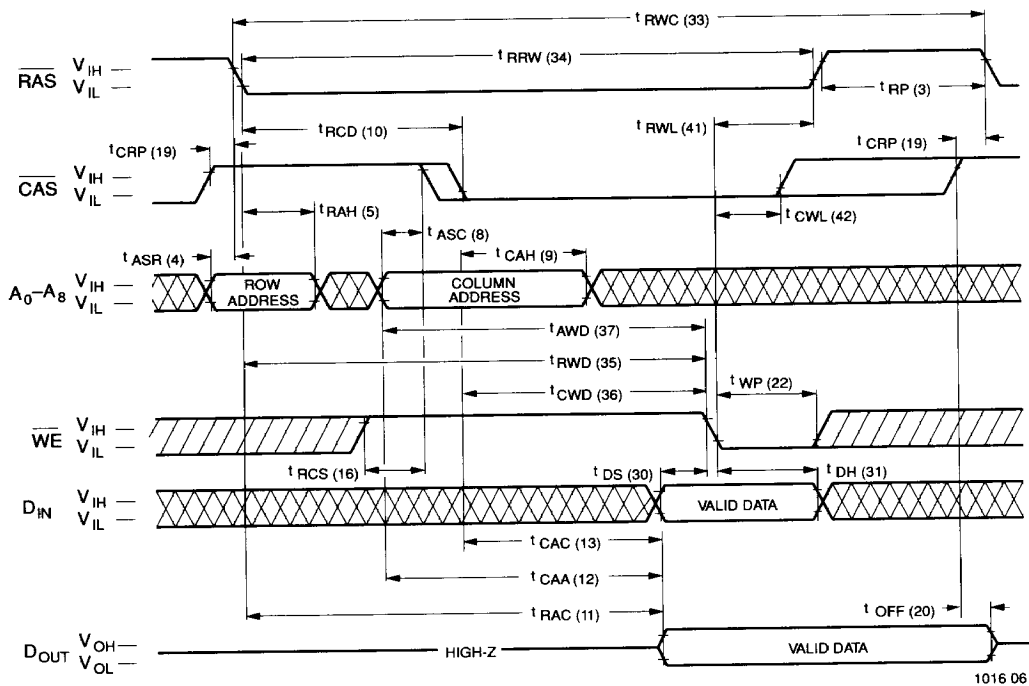
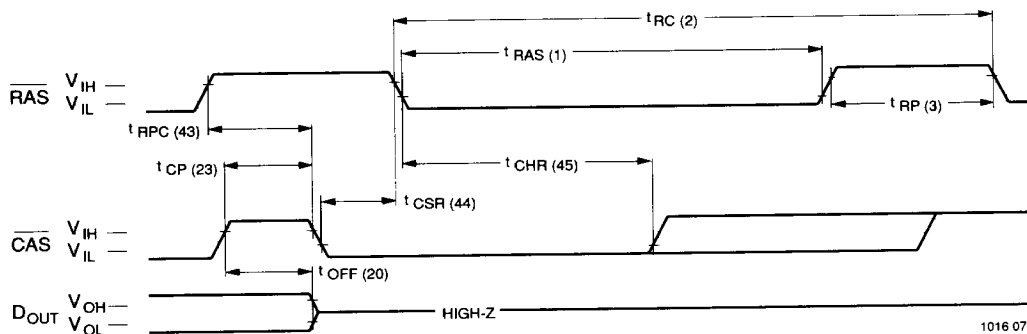
**Waveforms of Read Cycle**



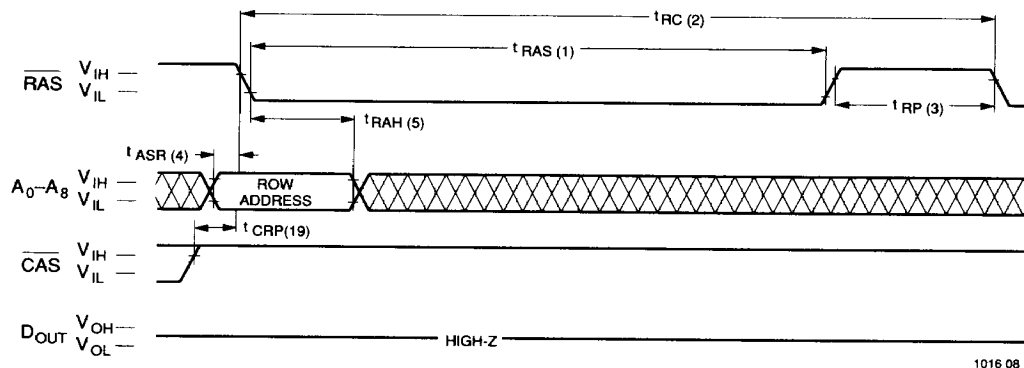
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**Waveforms of Early Write Cycle**

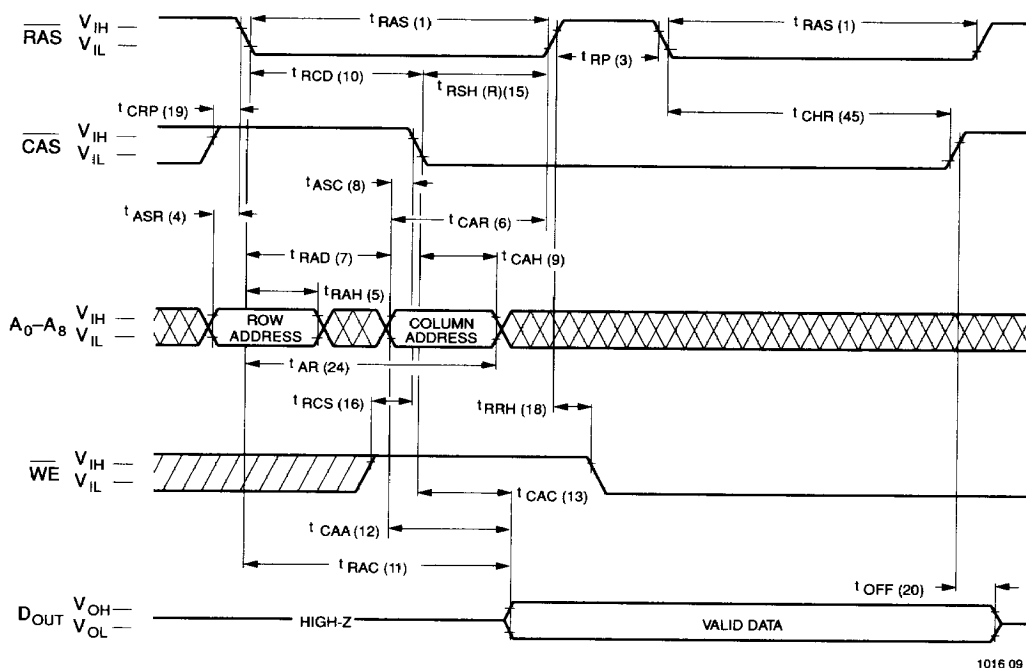


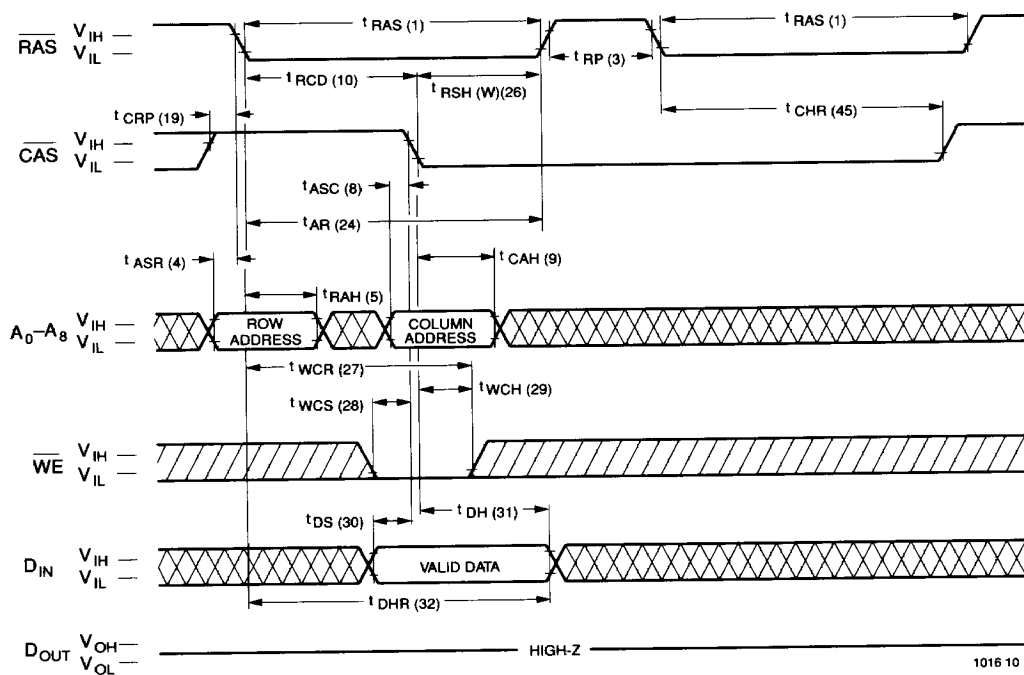
**Waveforms of Read-Modify-Write Cycle****Waveforms of RAS-Only Refresh Cycle**

### Waveforms of CAS-before-RAS Refresh Cycle

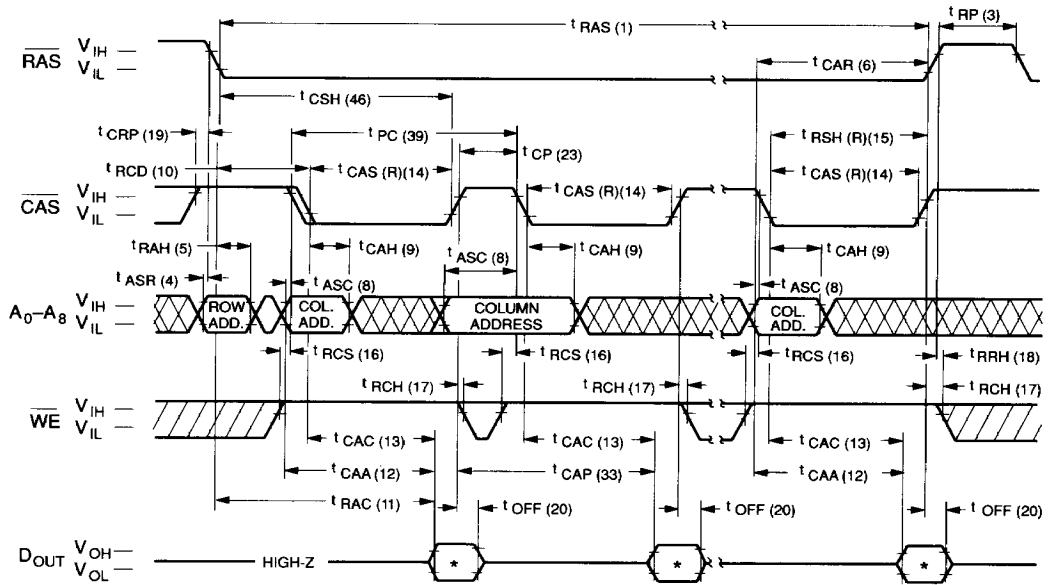

**2**

### Waveforms of Hidden Refresh Cycle (Read)



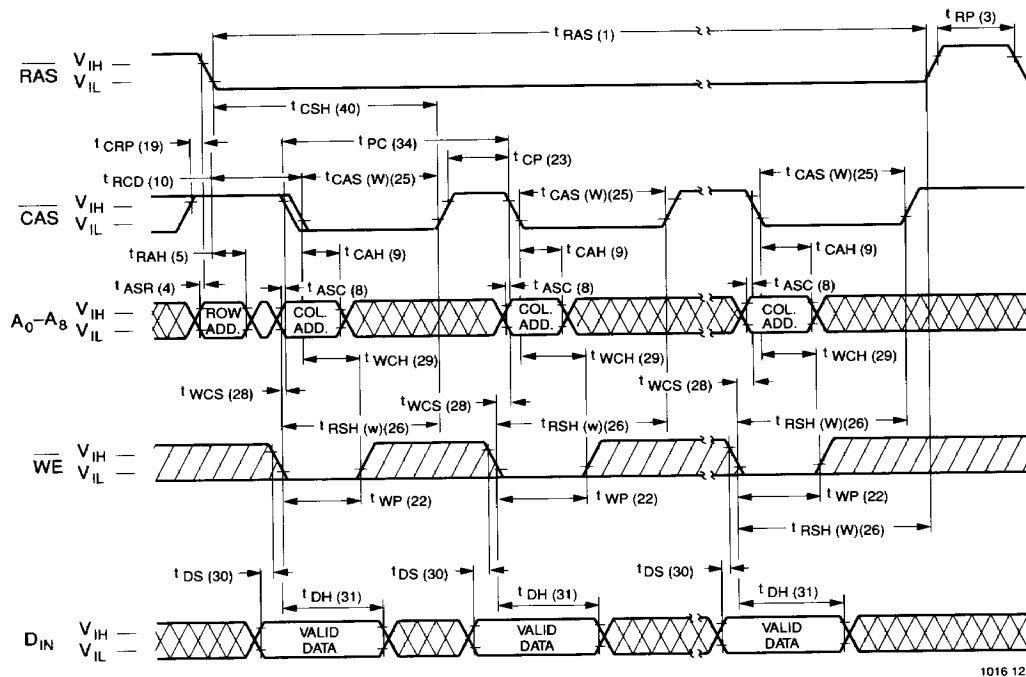
**Waveforms of Hidden Refresh Cycle (Write)**


1016 10

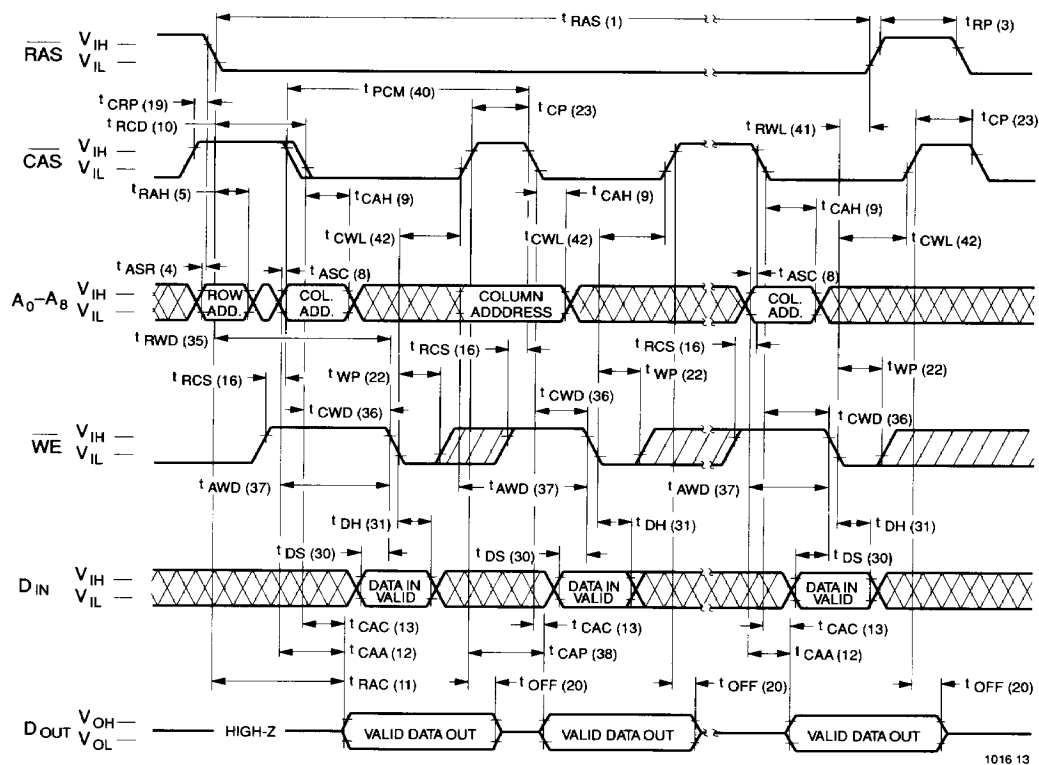
**Waveforms of Fast Page Mode Read Cycle**


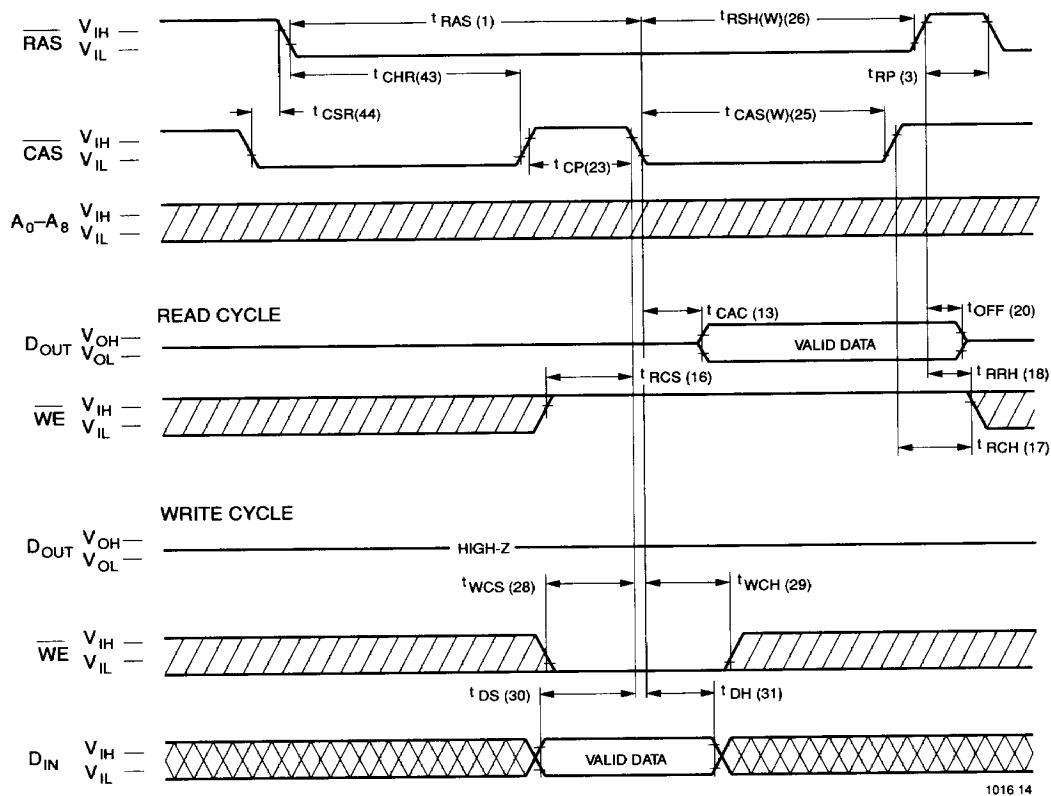
\* Valid Data

1016 11

**Waveforms of Fast Page Mode Write Cycle**


1016 12

**Waveforms of Fast Page Mode Read-Modify-Write Cycle**

**2**

**Waveforms of Refresh Counter Test Cycle**




## Functional Description

The V53C256A is a CMOS dynamic RAM optimized for high data bandwidth, low power applications. It is functionally similar to a traditional dynamic RAM. The V53C256A reads and writes data by multiplexing an 18-bit address into a 9-bit row and a 9-bit column address. The row address is latched by the Row Address Strobe ( $\overline{\text{RAS}}$ ). The column address flows through an internal address buffer and is latched by the Column Address Strobe ( $\overline{\text{CAS}}$ ). Because access time is primarily dependent on a valid column address rather than the precise time that the  $\overline{\text{CAS}}$  edge occurs, the delay from  $\overline{\text{RAS}}$  to  $\overline{\text{CAS}}$  has little effect on the access time.

## Memory Cycle

A memory cycle is initiated by bringing  $\overline{\text{RAS}}$  low. Any memory cycle, once initiated, must not be ended or aborted before the minimum  $t_{\text{RAS}}$  time has expired. This ensures proper device operation and data integrity. A new cycle must not be initiated until the minimum precharge time  $t_{\text{RP}}/t_{\text{CP}}$  has elapsed.

## Read Cycle

A read cycle is performed by holding the Write Enable ( $\overline{\text{WE}}$ ) signal high during a  $\overline{\text{RAS}}$ / $\overline{\text{CAS}}$  operation. The column address must be held for a minimum time specified by  $t_{\text{AR}}$ . Data Out becomes valid only when  $t_{\text{RAC}}$ ,  $t_{\text{CAA}}$ , and  $t_{\text{CAC}}$  are all satisfied. As a result, the access time is dependent on the timing relationships between  $t_{\text{RAC}}$ ,  $t_{\text{CAA}}$ , and  $t_{\text{CAC}}$ . For example, the access time is limited by  $t_{\text{CAA}}$  when  $t_{\text{RAC}}$  (min.) and  $t_{\text{CAC}}$  (min.) are both satisfied.

## Write Cycle

A write cycle is performed by taking  $\overline{\text{WE}}$  and  $\overline{\text{CAS}}$  low during a  $\overline{\text{RAS}}$  operation. The column address is latched by  $\overline{\text{CAS}}$ . The write can be  $\overline{\text{WE}}$  controlled or  $\overline{\text{CAS}}$  controlled depending on whether  $\overline{\text{WE}}$  or  $\overline{\text{CAS}}$  falls later. Consequently, the input data must be valid at or before the falling edge of  $\overline{\text{WE}}$  or  $\overline{\text{CAS}}$ , whichever occurs last. In the  $\overline{\text{CAS}}$ -controlled write cycle when the leading edge of  $\overline{\text{WE}}$  occurs prior to the  $\overline{\text{CAS}}$  low transition, the output ( $\text{D}_{\text{OUT}}$ ) pin will be in the High-Z state at the beginning of the Write function. Ending the write with  $\overline{\text{RAS}}$  or  $\overline{\text{CAS}}$  will maintain the output in the High-Z state.

## Refresh Cycle

To retain data, 256 refresh cycles are required in each 4 ms period. There are two ways to refresh the memory:

1. By clocking each of the 512 row addresses ( $\text{A}_0$  through  $\text{A}_7$ ) with  $\overline{\text{RAS}}$  at least once every 4 ms. Any Read, Write, Read-Modify-Write or  $\overline{\text{RAS}}$ -only cycle refreshes the addressed row.
2. Using a  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  Refresh Cycle. If  $\overline{\text{CAS}}$  makes a transition from low to high to low after the previous cycle and before  $\overline{\text{RAS}}$  falls,  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh is activated. The V53C256A will use the output of an internal 8-bit counter as the source of row addresses and ignore external address inputs.

$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  is a "refresh-only" mode and no data access or device selection is allowed. Thus,  $\text{D}_{\text{OUT}}$  will remain in the High-Z state during the cycle.

A  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  counter test mode is provided to ensure reliable operation of the internal refresh counter. The user can use the counter test mode to write consecutive data patterns (256 write cycles) and then verify the written data by applying 256 consecutive read cycles. In this mode, the V53C256A ignores external row/column addresses and takes the output from the internal counter instead.

## Data Retention Mode

The V53C256A offers a CMOS standby mode that is entered by causing the  $\overline{\text{RAS}}$  clock to swing between a valid  $\text{V}_{\text{IL}}$  and an "extra high"  $\text{V}_{\text{IH}}$  within 0.2 V of  $\text{V}_{\text{DD}}$ . While the  $\overline{\text{RAS}}$  clock is at the "extra high" level, the V53C256A power consumption is reduced to the low  $\text{I}_{\text{DD6}}$  level. Overall  $\text{I}_{\text{DD}}$  consumption when operating in this mode can be calculated as follows:

$$I = \frac{(t_{\text{RC}}) \times (\text{I}_{\text{DD1}}) + (t_{\text{RX}} - t_{\text{RC}}) \times (\text{I}_{\text{DD6}})}{t_{\text{RX}}}$$

Where  $t_{\text{RC}}$  = Refresh Cycle Time  
 $t_{\text{RX}}$  = Refresh Interval / 256

### Fast Page Mode Operation

Fast Page Mode operation permits all 512 columns within a selected row of the device to be randomly accessed at a high data rate. Maintaining  $\overline{\text{RAS}}$  low while performing successive  $\overline{\text{CAS}}$  cycles retains the row address internally and eliminates the need to reapply it for each cycle. The column address buffer acts as a transparent or flow-through latch while  $\overline{\text{CAS}}$  is high.

Thus, access begins at the occurrence of a valid column address rather than at the falling edge of  $\overline{\text{CAS}}$ , eliminating  $t_{\text{ASC}}$  and  $t_{\text{T}}$  from the critical timing path.  $\overline{\text{CAS}}$  latches the address into the column address buffer and acts as an output enable.

During Fast Page Mode operation, Read, Write, Read-Modify-Write, or Read-Write-Read cycles are possible at random addresses within a row. Following the initial entry cycle into Fast Page Mode, access is  $t_{\text{CAA}}$  or  $t_{\text{CAP}}$  controlled. If the column address is valid prior to the rising edge of  $\overline{\text{CAS}}$ , the access time is determined by the  $\overline{\text{CAS}}$  rising edge. If the column address is valid after the rising edge of  $\overline{\text{CAS}}$ , the access is timed from the occurrence of the valid address and is specified by  $t_{\text{CAA}}$ . In both cases, the falling edge of  $\overline{\text{CAS}}$  latches the address and enables the output.

Fast Page Mode provides a sustained data rate of over 19 MHz for applications that require high data rates like bit-mapped graphics or high-speed signal processing. The following equation can be used to calculate the data rate:

$$\text{Data Rate} = \frac{512}{t_{\text{RC}} + 511 \times t_{\text{PC}}}$$

### Data Output Operation

The V53C256A Data Output pin ( $\text{D}_{\text{OUT}}$ ) has a three-state capability and is controlled by  $\overline{\text{CAS}}$ . When  $\overline{\text{CAS}}$  is high ( $\geq V_{\text{IH}}$ ), the output is in the High-Z state. Table 1 summarizes the  $\text{D}_{\text{OUT}}$  states possible for various memory cycles.

### Power-On

After application of the  $V_{\text{DD}}$  an initial pause of 200  $\mu\text{s}$  is required followed by a minimum of 8 initialization cycles (any combination of cycles containing a  $\overline{\text{RAS}}$  clock). Eight initialization cycles are required after extended periods of bias without clocks (greater than the Refresh Interval). During Power-On, the  $V_{\text{DD}}$  current requirement of the V53C256A is dependent on the input levels of  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$ . If  $\overline{\text{RAS}}$  is low during power on, the device will go into an active cycle and  $I_{\text{DD}}$  will exhibit current transients. It is recommended that  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  track with  $V_{\text{DD}}$  or be held at a valid  $V_{\text{IH}}$  during Power-On to avoid current surges.

**Table 1. Vitellic V53C256A Data Output Operation for Various Cycle Types**

| Cycle Type                                                             | $\text{D}_{\text{OUT}}$ State     |
|------------------------------------------------------------------------|-----------------------------------|
| Read Cycles                                                            | Data from Addressed Memory Cell   |
| $\overline{\text{CAS}}$ -Controlled Write Cycle (Early Write)          | High-Z                            |
| $\overline{\text{WE}}$ -Controlled Write Cycle (Late Write)            | Active, not valid                 |
| Read-Modify-Write Cycles                                               | Data from Addressed Memory Cell   |
| Fast Page Mode Read Cycle                                              | Data from Addressed Memory Cell   |
| Fast Page Mode Write Cycle (Early Write)                               | High-Z                            |
| Fast Page Mode Read-Modify-Write Cycle                                 | Data from Addressed Memory Cell   |
| $\overline{\text{RAS}}$ -only Refresh                                  | High-Z                            |
| $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ Refresh Cycle | Data remains as in previous cycle |
| $\overline{\text{CAS}}$ -only Cycles                                   | High-Z                            |